

Thermal Analysis of an Electrical Traction Motor with an Air Cooled Rotor

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Abstract—At low vehicle speed typical for urban areas the thermal limits of the electrical machine are mostly not reached due to the thermal time constants being much higher than the short time spans of high power demand. However in a highway scenario a higher power is required continuously. Due to rotor iron losses caused by the high frequency of the modern traction drive and the thermally insulating air gap at high speeds the rotor is the crucial element in terms of temperature. In this paper the effect of an interior rotor air cooling to improve the thermal utilization is studied.

Index Terms—Electric Vehicles, Traction Drives, Rotating Electrical Machines, Permanent Magnet Synchronous Machines, Thermal Management, Rotor Air Cooling

I. INTRODUCTION

Various studies on the thermal behavior and overload capability of electrical machines can be found in literature [1] [2]. In [3] a convection cooled machine is investigated, intended for use in an range extender module with a rated speed of 2750 min^{-1} . This is much lower than modern traction drives featuring a speed in the range of $11\,300 \text{ min}^{-1}$ (Renault Zoe), $11\,400 \text{ min}^{-1}$ (BMW i3, Nissan Leaf) or $12\,000 \text{ min}^{-1}$ (Tesla Model S, Smart Electric Drive). In [4] the thermal behavior of a traction drive with a rated power of 46 kW and a maximum speed of 6000 min^{-1} is analyzed. However studies of the thermal behavior of the rotor of radial field machines which consider high machine speed are rare, despite the rotor being the limiting factor for power output at this speed. To improve the thermal utilization of the electrical machine the effect of an integrated rotor air cooling system is analyzed and the possible load determined.

II. APPROACH

To determine the possible load the machine temperatures are calculated and compared to the permitted temperatures. Therefor a lumped parameter thermal model (LPTN) is established. Model parameters with significant uncertainties, in particular the convection coefficients and thermal properties of the winding and grouting, are estimated with an optimization algorithm on a series of eight different measurements. As starting point for the convection coefficients analytical and empirical approaches from [5] [6] are used. The distribution

of the iron losses is calculated using finite element analysis (FEA) in combination with the iron loss formula from [7]. The material iron loss parameters from that paper were fitted to a measured map of the total iron losses of the machine. For more details about thermal simulation see for example [8].

The insulation system of the winding is classified for 180°C (DIN EN 60085 [10]). High temperatures lead to accelerated aging and reduced life time, therefor this limit is used. With a method for calculating the aging effects higher short time temperature limits could be allowed. The permitted permanent magnet temperature depends on the counter acting magnetic field, therefore at low magnet temperatures a higher load can be tolerated. In contrast to the winding exceeding the temperature limit leads to irreversible demagnetization. Using FEA and the permanent magnet characteristic an allowed temperature for every operating point is determined. Since the permanent magnet characteristic is not ideal linear, a small demagnetization of 0.1 % is allowed.

III. PERMANENT MAGNET SYNCHRONOUS MACHINE WITH AIR COOLED ROTOR

The studied machine is an radial flux PMSM with internal magnets. Main machine parameters are collected in table I. The rotor air cooling system is constructed internally inside the shaft, with air intake and output on the same side. In the harsh environment of a vehicle the air can be loaded with water, salt or other aggressive substances. The advantage of this concept is a separation of the air flow from the sensitive active components. Therefor a less complex air filter system is sufficient.

The hollow shaft features aluminum cooling fins on the inside. Through the rotation of the fins and the static guidance

TABLE I
MAIN MACHINE PARAMETERS

Rated power	30 kW	Yoke outer diameter	202 mm
Rated torque	100 Nm	Air gap diameter	122 mm
Max. speed	$10\,000 \text{ min}^{-1}$	Shaft inner diameter	82 mm
Pole pairs	3	Active length	80 mm
Slots	36		

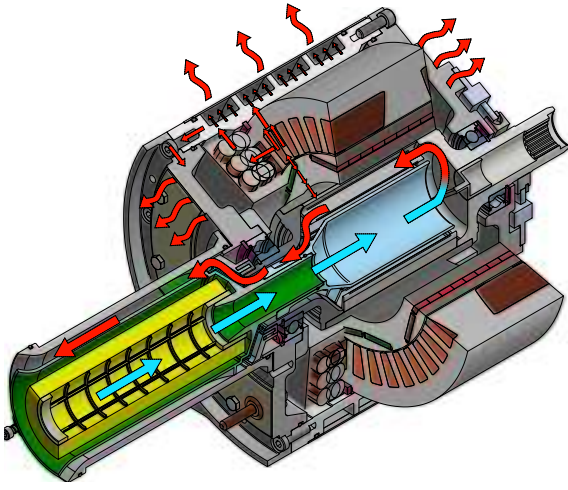


Fig. 1. Machine design with rotor air cooling system.

plates of the tube inside the shaft a speed dependent air flow is achieved. In addition to the cooling of the electrical machine the air flow is used to cool the inverter system, which is mounted circularly around the intake/output tube. The system is illustrated in Fig. 1, the inverter itself is not shown. Further information on the machine can be found in [9].

IV. THERMAL MODEL

A rotational electrical machine features a good radial symmetry to the rotational axis, and to some degree a symmetry to the axial center plane depending on the endwindings, shaft and endshield with bearings. In this paper it is taken advantage of these symmetries for simplification of the model structure. The LPTN is shown in fig. 3, and a sketch to illustrate the areas/volumes represented by the distinct nodes is given in fig. 2.

The heat path in radial direction is represented in fig. 3 by the resistances and thermal masses in vertical direction. For the axial direction it is assumed that in the stacked sheet metal the heat flow is zero. This assumption is feasible due to two reasons: 1. The thermally insulating varnish layers reduce the thermal conductivity of the iron core, and 2. the heat

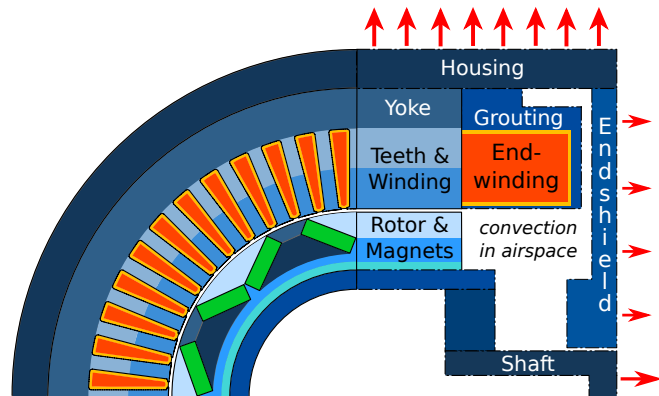


Fig. 2. Sketch of cross section and longitudinal section of the Machine to illustrate the structure of the thermal model.

is primarily dissipated through the water cooling jacket and the rotor cooling, therefore in axial direction the temperature gradient is low.

Table II lists some thermal conductivities and convection coefficients which were in combination with the machine dimensions used to calculate the thermal resistances. The rotor cooling was modeled with the MATLAB/Simscape thermal fluid box and the parameters again fitted with measurements, so no simple convection coefficient can be given.

In fig. 4 the fitted convection coefficient for the airgap is shown which is implemented as a saturation formula based on the approach in [6].

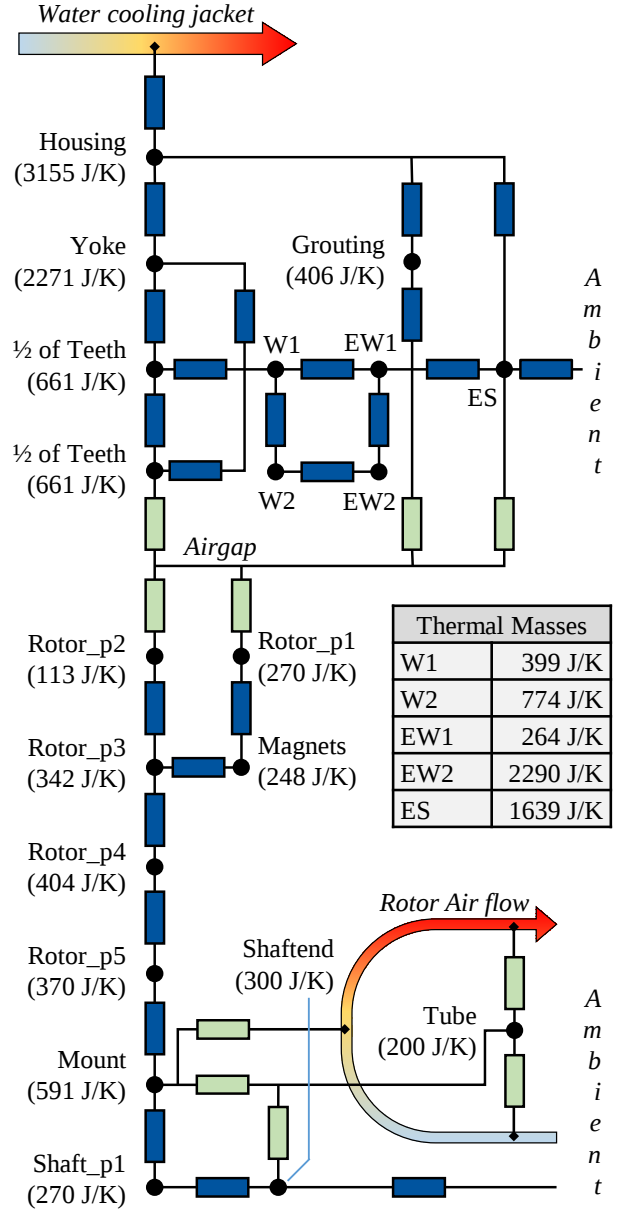


Fig. 3. Schematic diagram of the LPTN considered. Black nodes are thermal capacitors, light green resistances indicate a variable resistance representing machine speed dependent convection.

TABLE II
MAIN MACHINE PARAMETERS

	Thermal conductivity or convection coefficient
Water Jacket	503 W/m ² K (full Housing cylinder)
Sheet Metal	23 W/mK (in sheet plane)
Winding	174 W/mK (axial direction)
	12 W/mK (radial direction)
Grouting	1 W/mK

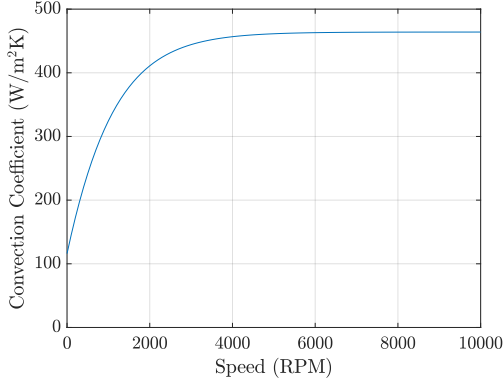


Fig. 4. Fitted convection coefficient in airgap over machine speed.

V. VALIDATION OF THE THERMAL MODEL

Measured and simulated temperatures for four measurement series are given in Fig. 5-8. The measured temperatures are from six sensors in the end winding on one axial machine end, two sensors in magnet recesses and one sensor between the shaft and the rotor core.

The measured temperatures at the six end winding sensors show consistent differences of up to 20 K which indicates a dependency of the local positioning of the sensor. Insulation aging and possible failure will occur primarily at the end winding hot spots, therefore the measurement data from the hotter three sensors is used for parameter identification of the thermal model.

The model with identified parameters shows good accordance to the measurements with deviations lower than the local temperature differences. The accordance also applies for different operating points with different loss-distributions, different coolant temperatures, with or without rotor cooling. The impact of the iron loss distribution can be observed in Fig. 7. At the time instant of "minute 27" the model shows slightly lower temperatures than measured. A decrease of load does not change the thermal properties which are constant or speed dependent (convection), but leads to slightly higher temperatures in comparison to the measurement at "minute 47". This leads to the conclusion of deviations in the iron loss calculation from the real iron loss distribution.

VI. EFFECT OF THE ROTOR AIR COOLING SYSTEM

The rotor cooling yields a significant temperature decrease of the magnets depending on the operating point. Because of the speed dependent flow rate the biggest temperature decrease

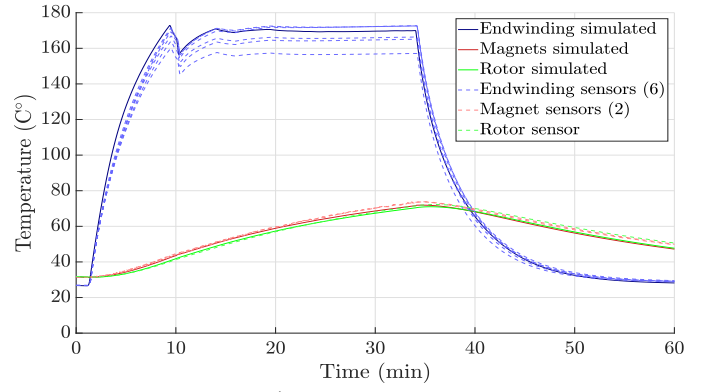


Fig. 5. High load at 50 min⁻¹ with high copper losses. Water coolant intake at 20 °C, rotor cooling active.

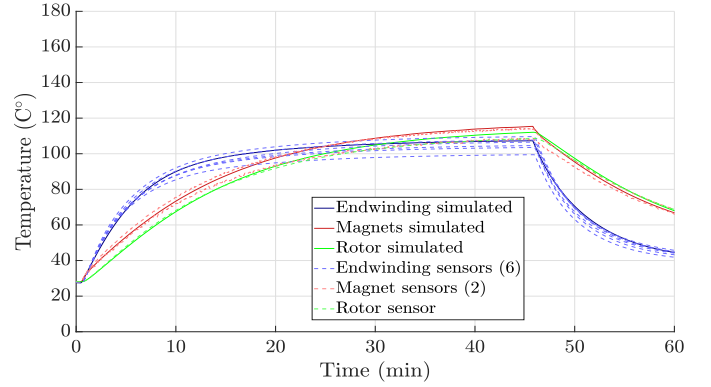


Fig. 6. High load at 9500 min⁻¹ with high iron losses. Water coolant intake at 80 °C, rotor cooling not active.

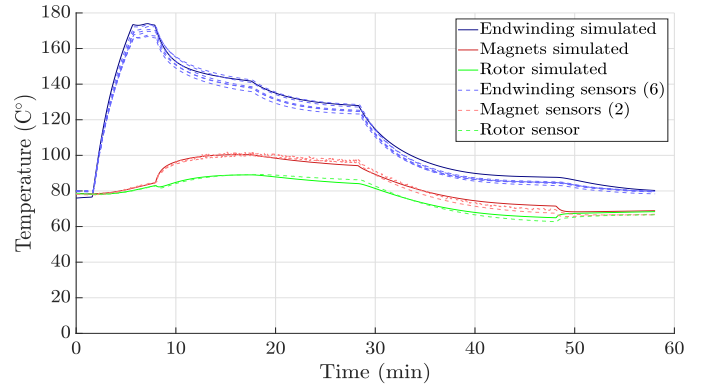


Fig. 7. High load at 50 min⁻¹, from min. 8 on at 8000 min⁻¹ with step wise decreasing load. Water coolant intake at 80 °C.

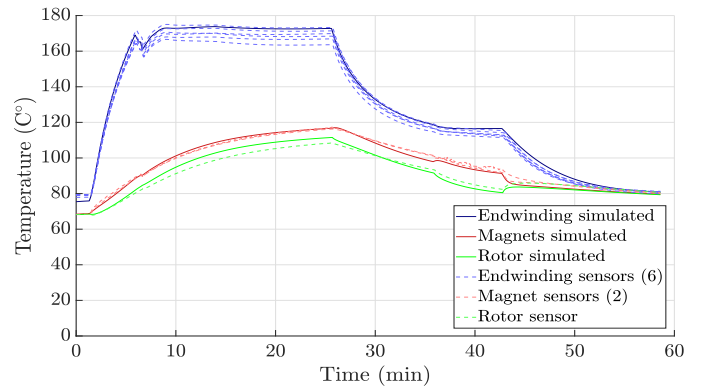


Fig. 8. High load at 4000 min⁻¹, then 6000 min⁻¹, then 9500 min⁻¹. Water coolant intake at 80 °C.

VII. CONCLUSION

In this paper the effect of an air cooled rotor on the possible operation areas of a radial flux PMSM is investigated via thermal simulation. The rotor cooling yields a significant decrease in magnet temperature at high machine speed. This effectively enlarges the area of possible continuous operation as well as the possible overload. Due to the speed dependent cooling behavior the effect is largest at high machine speed which occurs at high vehicle speed where a high power output is required and cooling of the rotor is crucial. The results show a significant increase in thermal utilization of the motor.

VIII. ACKNOWLEDGEMENT

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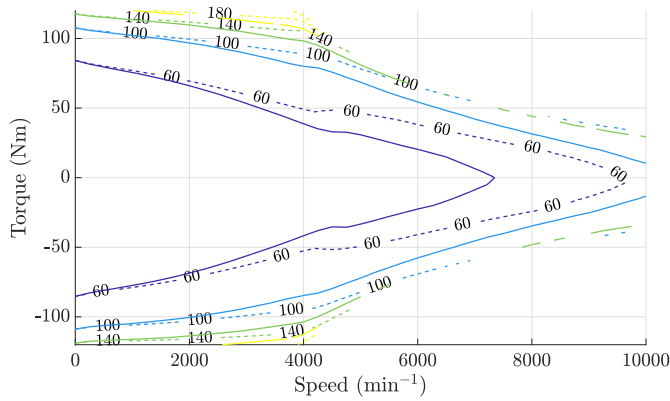


Fig. 9. Steady-state temperature of the permanent magnets with and without rotor cooling.

occurs at $10\,000\text{ min}^{-1}$ with more than 40 K difference to the non cooled rotor (see Fig. 9).

To illustrate impact of the temperature decrease the areas of possible continuous operation (S1) with and without rotor cooling (RC) have been calculated. Figure 10 shows that at $10\,000\text{ min}^{-1}$ the continuously possible torque or rather the power output rises by about 50 %. Via simulation with a vehicle model of a common passenger car the continuous speed line was calculated below which a vehicle would decelerate. Also shown are the permitted magnet temperatures from the FEA simulation.

The rotor air cooling system significantly enlarges the area of continuous operation (S1 area) and therefore also the possible overload. It has to be mentioned that the water coolant intake temperature is the standardized 25°C for determining the load capability of electrical machines. With a vehicle cooling system the coolant intake temperature is expected to be notably higher, reducing the heat removal through the water cooling jacket. This will further increase the effect of the rotor cooling.

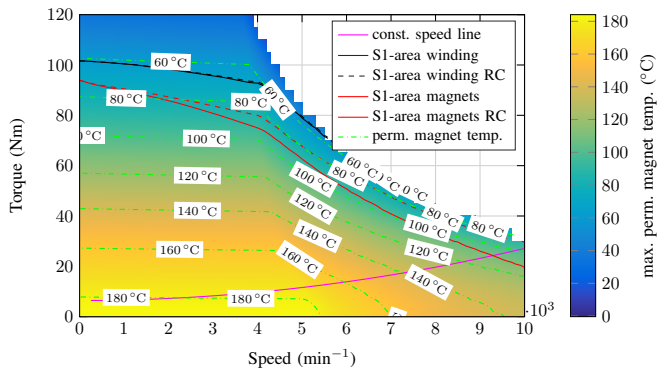


Fig. 10. Possible operation areas and permitted magnet temperatures. Coolant intake at 25°C .